

pco.[®]

pco.vision Camera Control Software

FOR WINDOWS AND LINUX




excelitas[®]

Excelitas PCO GmbH asks you to carefully read and follow the instructions in this document.
For any questions or comments, please feel free to contact us at any time.

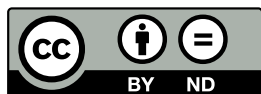


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pco.vision user manual 1.1.1

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1 Introduction

This manual describes the operation of the software application pco.vision developed by Excelitas PCO. With this software, all current and most older PCO cameras can be operated.

This manual covers the software functions, while specific camera data and values can be found in the corresponding camera manual.



Not all software functions are supported on all camera models.

1.1 Supported operating systems

This software applications is available for the following operating systems¹:

- Windows (64-bit)
- Ubuntu (64-bit)
- Debian (64-bit)
- Rocky/Red Hat (64-bit)

This section lists the currently supported operating systems, runtimes, and tools as well as planned support changes.

Operating systems

OS	Minimum supported	Latest supported	Planned
Debian LTS	11 (until 2026)	12	13 (2026)
Ubuntu LTS	20 (until 2026)	22	24 (2026)
Redhat	8 (until 2026)	9	10 (2026)
Windows	10 (until 2027)	11	Not planned

Runtimes/Tools

Name	Minimum supported	Latest supported	Planned
Python	3.8 (until 2026)	3.12	3.13 (2027)
.Net Framework	4.6 (until 2026)	4.8.1	Not planned
cMake	3.20	—	Not planned
GPU CC	5.0 (until 2026)	—	7.0 (2026)

1.2 Installation

This software application enables you to control camera parameters and settings from Microsoft Windows or Linux operating systems. Images can be displayed on a monitor and may be downloaded and stored.

¹It is recommended to only use currently supported operating systems.



1.3 Windows

[Download](#) the **pco.vision Windows** package, unzip it, and execute it. Follow the installation wizard:

- 1 Select *"Install for anyone using this computer"* to install to the Program Files folder, otherwise it will be installed only to your user folder.
- 2 In the Choose components window, select additional drivers if needed: **Silicon Software DLL MeIV** for Camera Link interface or **Camera Link HS DLL CLHS** for Camera Link HS interface (for USB and USB3 the driver must be installed separately).
- 3 Choose install directory.
- 4 Click *"Install"* and after the next two screens installation is complete.

After a successful installation, you will find the program folder PCO Digital Camera Toolbox in the selected install directory (by default, Program Files) and a PCO software icon on your desktop.

To uninstall the pco.vision application, open 'Installed Apps' in Windows Settings (formerly 'Apps & features').

1.4 Linux

This software application supports multiple Linux distributions. [Download](#) the **pco.vision Linux** package that is compatible with your system from our website.

Ubuntu/Debian [Download](#) the *.deb package for **pco.vision**.

- 1 Install the dependencies:

```
sudo apt-get update && apt-get install libusb-1.0-0-dev, libxcb-cursor0
```

- 2 Install the *.deb file using:

```
sudo apt-get install ./pco.vision_*.deb
```

Rocky/Red Hat [Download](#) the *.rpm package for **pco.vision**. Install the file using:

```
sudo dnf install ./pco-vision-*.rpm
```



2 Quick start

To get familiar with your new camera and software, it is recommended to first aim the camera at an object that is visible under normal light conditions as well as easy to focus on.

2.1 Preparation

- 1 Computer is turned on.
- 2 Installation of **pco.vision** and camera specific driver is finished.
- 3 An appropriate lens is attached (remove cap) or the camera is attached properly to the microscope, spectrograph or other scientific device.
- 4 Camera is connected to the computer.
- 5 Camera is connected to the power supply and powered up.

2.2 First image

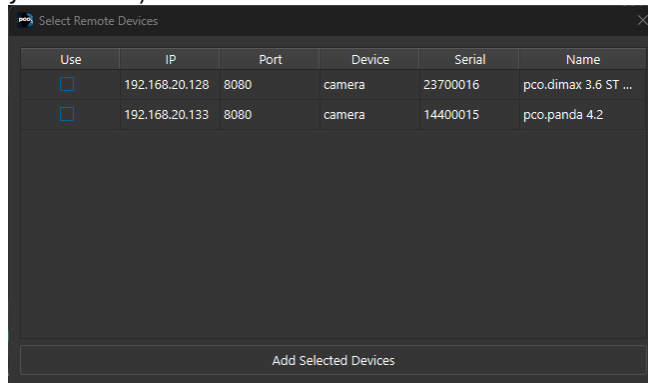
Working with a local camera:

- 1 Start **pco.vision**.
- 2 A **View Window** is displayed (if not, go to the main toolbar and click **View**, **View Windows**, then select the camera in the list).
- 3 Start **Preview** by clicking .
- 4 If the image is still too dark or too bright, adjust the **Exposure** time (chapter [3.3.2](#)) and the aperture and focus of the mounted lens.
- 5 Keep on adjusting until the object is in focus and can be seen clearly.

Working with a remote camera (requirement: [pco.server](#) is already running correctly):

- 1 Go to **pco_vision_setup.ini** and set `Searchmode=all`. Windows folder: `C:\ProgramData\pco` Ubuntu default: `~/ .config/pco/`
- 2 Start **pco.vision**.

- 3 A **Select Remote Device Window** is displayed (if not, check that you can ping the remote IP from your device). Select at least one camera.



- 4 Start **Preview** by clicking .
- 5 If the image is still too dark or too bright, adjust the **Exposure** time (chapter [3.3.2](#)) and the aperture and focus of the mounted lens.
- 6 Keep on adjusting until the object is in focus and can be seen clearly.

To learn how to record and save images, go to chapter 3.3.4 and chapter 3.6.

3 pco.vision software

3.1 Camera Overview

The **Camera Overview** window controls how the camera properties are display. The color of the text for the properties associated with the selected camera can be specified. This is helpful when multiple cameras are connected, as each camera can be assigned a different color. There is also a box to select whether a histogram will be displayed for the selected camera.

3.2 View Window

Images from the selected camera are shown in the **View Window**.

To open a View Window for a selected camera, go to the View menu -> View Windows, and select the desired camera from the dropdown list. Read-only information on **Pixel Values**, **Image Stats**, and **Performance Stats** may be displayed in the lower left corner of the window. This information can be enabled or disabled in the right-click menu of the window.

Display Range

The settings to change the Display Range are also located in the right-click menu. Use these to adjust the display contrast.

- **Auto Range:** The display settings are adjusted based on the minimum and maximum pixel values detected.
- **3Sigma:** Display settings are based on the average pixel value +/- 3 sigma.
- **5Sigma:** Display settings are based on the average pixel value +/- 5 sigma.
- **Manual:** Enter the maximum and minimum values to display.

Zoom

Use the Zoom options in the right-click menu to zoom in or out of the image. Alternatively, you can also use the scroll wheel.

3.3 Camera Settings

The **Camera Settings** window is the main interface for all camera settings. These settings are applied to the active camera, selected from the camera list in the main toolbar.

A brief explanation of each setting is displayed as a tooltip when the cursor hovers over it.

The settings are divided into four categories: **Camera Info**, **Timing**, **Image**, and **Recording**.

To return all settings to default, click on **Reset to Default** at the bottom of the listed settings.

3.3.1 Camera Info

This section lists the name and serial number for the selected camera, along with the maximum frame rate possible when the current settings are applied. These parameters are read-only.



3.3.2 Timing

This is the section for setting both the **Exposure Time** and **Delay Time** and for selecting the **Pixel Rate** and the **Autoexposure** settings.

Exposure Time and **Delay Time**

The possible values for these parameters depend on the camera model. For line scan cameras those values are for single lines, independent of how many lines are recorded. The effective step size depends on internal camera constraints (usually in ns). If a value outside the supported range of the camera is entered, it is automatically adjusted to the nearest valid setting.

Values can be entered directly in the fields or adjusted stepwise using the up and down arrow controls.

Pixel Rate [MHz]

This setting sets the sensor readout speed. A higher pixel rate enables higher achievable frame rates, while a lower pixel rate may reduce image noise. The pixel rate (or scan rate) is fixed for certain camera models.

Conversion Factor

The conversion factor describes the relationship between collected charge and the resulting digital signal value. It indicates how many electrons correspond to one digital intensity level. This setting is used to switch between available gain modes, such as high-gain, low-gain, or low-light mode.

Autoexposure

If Autoexposure is enabled, this setting will find the optimal exposure time between the maximum and minimum time values specified. The pixel values are optimized for the specified region.

There are 4 different types of regions available:

- 'balanced' (default)
- 'center_based'
- 'corner_based'
- 'full'.

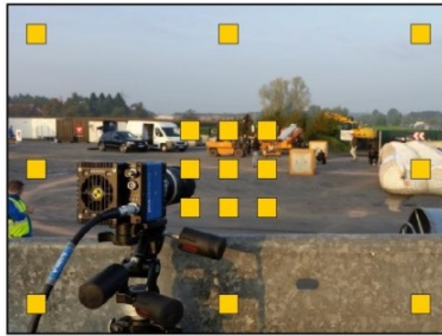
The size of the pixel clusters is fixed, but depends on the overall image size and is treated separately for width and height:

- For $\text{width/height} \geq 1300$ the cluster size is 100.
- For $1300 > \text{width/height} \geq 650$ the cluster size is 50.
- For $650 > \text{width/height} \geq 325$ the cluster size is 25.
- For $\text{width/height} < 325$ the cluster size is width/height.

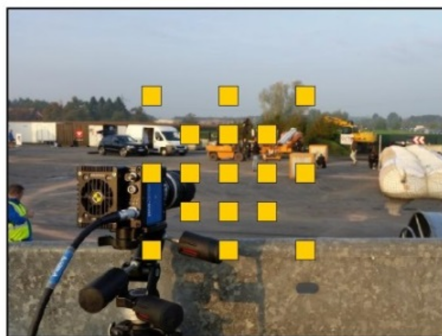
Balanced:

The measurement fields are positioned centrally and in all four corners.

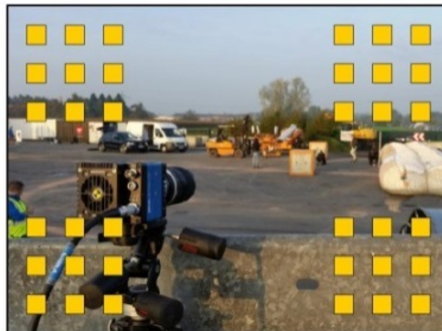


**Center-based:**

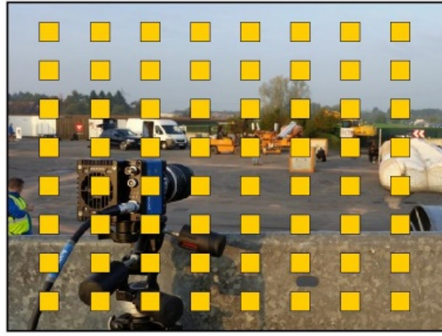
All measurement fields are positioned in the center.

**Corner-based:**

There are measurement fields positioned in all four corners.

**Full:**

The measurement fields are placed across the entire image.



Autoexposure may be switched on or off during recording, however its parameters can only be changed when recording is off.

3.3.3 Image

The Image section includes settings for the **Region of Interest (ROI)**, the **Timestamp** and the **Noise Filter**.

ROI

The **ROI** can be specified by entering the top, bottom, left and right coordinates of the ROI boundary.

Timestamp

This is used to add a **Timestamp** to the image. The timestamp is calculated by the camera firmware and added to the top, left section of the image. It can have various formats, though not all are supported in every camera model:

- **Off**: no stamp
- **Binary**: stamp is encoded as BCD, replacing the first 14 pixels of the image
- **Binary & ASCII**: ASCII characters are placed in the image to the right of the binary time stamp. These characters are human-readable and replace the image data.
- **ASCII**: ASCII characters are placed in the top, left corner of the image. These characters are human-readable and replace the image data.

Noise filter

The **Noise filter** can be turned on or off. This is a dynamic filter that can be activated to remove so-called blinkers and high-noise pixels. If you encounter unexpected aliasing effects, turn this filter off.

3.3.4 Recording

In this section, you can select the **Trigger Mode**, the **Record Mode**, how images will be stored by choosing the **File Format** and **Data Format**, as well as the **Image Count**.

Trigger Mode

A number of trigger modes are supported by this application:

- **Auto Sequence:** The camera determines the highest possible frame rate based on the set exposure time and the time required for a frame readout. When recording starts, continuous image acquisition begins and continues until recording stops.
- **Soft Trigger:** Only single images are captured in this mode. One image is acquired each time the **Trigger** button in the main toolbar is clicked.
- **Ext. Exp. Start:** In the External Exposure Start mode, single image recording is triggered by the rising edge of the signal at the input connector. The frame rate is defined by the frequency of the external signal. Exposure time and ROI settings affect the maximum possible frame rate.
- **Ext. Exp. Ctrl.:** In the External Exposure Control mode, single image recording is triggered by the rising edge of the signal at the input connector. The duration of exposure is also determined by the received signal, as it is ended when the falling edge of the signal is detected.

Record Mode

There are three record modes to choose from. Recording can be performed as a single **Sequence** or by a rotating **Ring Buffer**. Images can also be directly saved to disk when the **File** mode is selected.

- **Sequence:** The number of images specified in "Image Count" are acquired to memory, then the recording stops.
- **Ring Buffer:** The number of images specified in "Image count" are acquired to memory, then the images are overwritten from oldest to newest.
- **File:** The number of images specified in "Image Count" are directly saved on disk in the format selected in "File Format".

File Format

This is only available in Record Mode "File". Select the desired file format from the dropdown list.

Data Format

Depending on the camera model, the image data can be stored in different formats. Select the desired data format from the dropdown list.

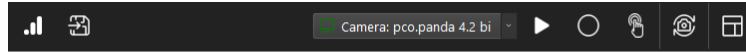
3.4 Video Control

The Video Control window controls the playback of recorded images. The slider can be used to scroll through the images. Controls are provided to playback the images in sequence and to step through the images.



3.5 Main toolbar

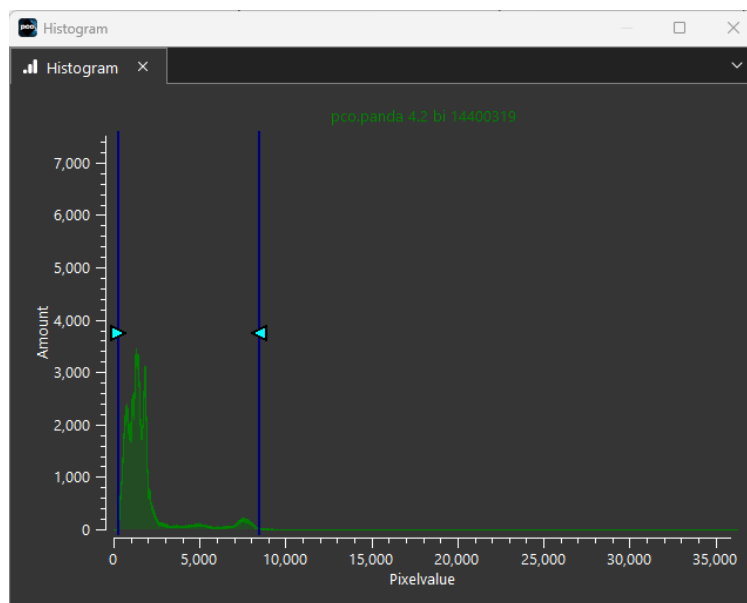
The main toolbar contains the Histogram, Save latest Image, Preview, Record, Trigger, Scan for Camera, and Perspective button and a dropdown menu with a list of all cameras.



3.5.1 Histogram button



Pressing this button opens a new window displaying histograms for all listed cameras with the histogram enabled. Vertical cursors are placed at the max and min points of the selected display range. Moving the cursors will adjust the display range.

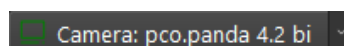


The histogram can be rescaled using the scroll wheel of the mouse. The scroll wheel adjusts the vertical scale, and Shift+scroll adjusts the horizontal scale. Alternatively, the horizontal scale can also be adjusted by right-clicking in the histogram window and entering the desired values.

After rescaling, the plot can be repositioned by dragging it with the mouse.

3.5.2 Camera list

The camera list is a dropdown menu on the main toolbar that allows you to select a connected camera. Selecting a camera updates the Camera Settings window to show that camera.



3.5.3 Preview button



Clicking the Preview button starts image acquisition for the selected camera. Preview images are displayed in real time to assist with camera setup and are not saved to memory or disk.

3.5.4 Record button



Pressing the Record button starts the camera and captures images as specified in the Camera Settings window.

3.5.5 Trigger button



Use the Trigger button to capture an image when the Soft Trigger mode is selected (see chapter 3.3.4 Trigger Modes).

3.5.6 Scan for Camera button



Pressing the **Scan for Camera** button prompts pco.vision to detect all cameras connected to any interface. All found cameras are added to the camera list on the main toolbar and the **View Windows** list in the **View** menu.

3.5.7 Perspective button



The **Perspective** button allows saving or restoring the configuration of the windows. This way it is possible to customize the look of the application for various use cases. If there are multiple users, each can configure the layout and save it for future use. Saved perspectives appear in the dropdown list at the bottom of the perspectives menu.

3.6 File menu

The **File** menu contains all options for saving images:

- **Save latest image:** Saves the currently displayed image directly to a preset folder in a preset format. On first use, you will be prompted to select the folder and format. If 'Save current image as' was used previously, those settings will be applied automatically.
- **Save current image as:** Saves the currently displayed image. A dialog opens for each image to select the folder and format.

- **Save all images:** Saves every image currently in the recorder memory. A dialog opens to select the folder and format for all images.

3.7 View menu

In the **View** menu, you can select which windows are displayed. Choose from **Camera Overview**, **Camera Settings**, **Video Control**, and the **View Windows** list. This list includes all detected cameras, as it is based on the Camera List in the main toolbar.

You can display a single window, multiple windows, or all windows at once. The layout of these windows can be customized by resizing, repositioning, or docking them to suit your workflow.

3.8 Color Theme menu

The look of the user interface can be changed by selecting one of the options in the **Color Theme** menu. The available themes are **PCO** (blue), **Green** and **Orange**.

3.9 Log Level menu

The settings in the **Log Level** menu are used to collect information on the camera environment and calls to the driver. This is useful in troubleshooting problems with the PCO cameras and software. The log level settings control the amount of detail in the logs. Detailed logs can help diagnose difficult problems, but a high level of detail can affect system performance, especially once the log files become very large. The available settings are:

- **Off:** No logging
- **Error:** Logs error messages
- **Warning:** Logs warnings from the driver
- **Info:** Logs system information
- **Debug:** Logs all relevant information.

The log files are located in the config/logging directory, i.e. C:\ProgramData\pco (Windows) or \\$.HOME/.pco/pco_logging/ (Linux).

3.10 Help menu

The Help menu displays the version information for pco.vision and provides a link to our website. There you can find driver and software updates.



About Excelitas®

Excelitas is a leading provider of advanced, life-enriching technologies that make a difference, serving global market leaders in the life sciences, advanced industrial, next-generation semiconductor and avionics end markets. Headquartered in Pittsburgh, PA, USA, Excelitas is an essential partner in the design, development and manufacture of advanced technologies, offering leading-edge innovation in sensing, detection, imaging, optics and specialty illumination for customers worldwide.

Excelitas is at the forefront of addressing many of the relevant megatrends impacting the world today, including precision medicine, industrial automation, artificial intelligence and connected devices (IoT).



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